

1. Liboff, problem 11.27 on page 498.

(a) Let A be an hermitian operator. We first demonstrate that

$$(e^{iA})^\dagger = e^{-iA}.$$

To prove this, we use the series expansion that defines the exponential,

$$e^{iA} = \sum_{n=0}^{\infty} \frac{(iA)^n}{n!}.$$

The sum converges for any operator A . Then,

$$e^{-iA} = \sum_{n=0}^{\infty} \frac{(-iA)^n}{n!} = \sum_{n=0}^{\infty} \frac{[(iA)^\dagger]^n}{n!} = \left[\sum_{n=0}^{\infty} \frac{(iA)^n}{n!} \right]^\dagger = (e^{iA})^\dagger,$$

where we have used the fact that $(iA)^\dagger = -iA^\dagger = -iA$, since A is hermitian. In the above derivation, we have also used the fact that $(A + B)^\dagger = A^\dagger + B^\dagger$, which also holds for the sum of an infinite number of terms, assuming that the sum converges.

A unitary operator \hat{U} is defined as an operator that satisfies $\hat{U}\hat{U}^\dagger = \hat{U}^\dagger\hat{U} = I$, where I is the identity operator. Defining $\hat{U} \equiv e^{iA}$, we see that:

$$\hat{U}\hat{U}^\dagger = e^{iA}(e^{iA})^\dagger = e^{iA}e^{-iA} = e^{i(A-A)} = e^0 = I. \quad (1)$$

In this derivation, I used the fact that for any two operators A and B ,¹

$$e^A e^B = e^B e^A = e^{A+B}, \quad \text{if and only if } AB = BA. \quad (2)$$

This result applies in eq. (1) since iA and $-iA$ clearly commute. Finally, we use the fact that $e^0 = I$, where 0 is the zero operator, which is again a consequence of the definition of the exponential of an operator via its series expansion.

Setting $A = -\hat{H}t/\hbar$, we note that if \hat{H} is hermitian, then so is A . It then follows that $\hat{U} = \exp(-i\hat{H}t/\hbar)$ is unitary.

(b) Given $|\psi(t)\rangle = \hat{U}|\psi(0)\rangle$, it follows that $\langle\psi(t)| = \langle\psi(0)|\hat{U}^\dagger$. Hence, using the results of part (a),

$$\langle\psi(t)|\psi(t)\rangle = \langle\psi(0)|U^\dagger U|\psi(0)\rangle = \langle\psi(0)|I|\psi(0)\rangle = \langle\psi(0)|\psi(0)\rangle.$$

That is, the normalization of ψ is independent of the time t .

¹For a proof of eq. (2), see, e.g., Jacob T. Schwartz, *Introduction to Matrices and Vectors* (Dover Publications, Inc., Mineola, NY, 2001) pp. 157–159, which can be viewed at <http://books.google.com>.

2. Liboff, problem 11.39 on page 512.

(a) We are given a wave function of a rigid rotator,

$$\psi(t) = \frac{1}{\sqrt{14}} \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} e^{-iEt/\hbar}, \quad E \equiv \hbar^2/I.$$

Using the results of Liboff, problem 11.38, we can write at time $t = 0$:

$$\frac{1}{\sqrt{14}} \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = -\frac{1}{\sqrt{7}} \xi_x^{(0)} + \frac{1}{\sqrt{7}} (\sqrt{2} - 1) \xi_x^{(-1)} + \frac{1}{\sqrt{7}} (\sqrt{2} + 1) \xi_x^{(1)},$$

where,

$$\xi_x^{(0)} \equiv \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \quad \xi_x^{(-1)} \equiv \frac{1}{2} \begin{pmatrix} 1 \\ -\sqrt{2} \\ 1 \end{pmatrix}, \quad \xi_x^{(1)} \equiv \frac{1}{2} \begin{pmatrix} 1 \\ \sqrt{2} \\ 1 \end{pmatrix},$$

are eigenstates of \hat{L}_x , with eigenvalues, 0 , $-\hbar$ and $+\hbar$, respectively. Note that the $\xi_x^{(m)}$ are all eigenstates of \vec{L}^2 with eigenvalue $2\hbar^2$. Thus,

$$\psi(t) = \left[-\frac{1}{\sqrt{7}} \xi_x^{(0)} + \frac{1}{\sqrt{7}} (\sqrt{2} - 1) \xi_x^{(-1)} + \frac{1}{\sqrt{7}} (\sqrt{2} + 1) \xi_x^{(1)} \right] e^{-iEt/\hbar}$$

since the energy E is independent of the value of m . The probability that a measurement L_x finds a value $-\hbar$ is simply the absolute square of the coefficient of $\xi_x^{(-1)}$, namely

$$\frac{1}{7}(\sqrt{2} - 1)^2 = \frac{3 - 2\sqrt{2}}{7}.$$

(b) After the measurement finds the value of $L_x = -\hbar$, the state of the system is given simply by $\xi_x^{(-1)}$. Including the time-dependent factor, $e^{-iEt/\hbar}$, the column vector representation of the state is:

$$\frac{1}{2} \begin{pmatrix} 1 \\ -\sqrt{2} \\ 1 \end{pmatrix} e^{-iEt/\hbar},$$

up to an overall unobservable phase factor.

3. Prove the following identities involving the Pauli spin matrices.

$$(a) \sigma_i \sigma_j = \delta_{ij} I + i \sum_{k=1}^3 \epsilon_{ijk} \sigma_k,$$

This identity is verified by explicitly multiplying the 2×2 matrices, $\sigma_i \sigma_j$, in the nine possible cases for $i, j = 1, 2, 3$. Using

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix},$$

it is easy to obtain:

$$\begin{aligned} \sigma_1 \sigma_2 &= -\sigma_2 \sigma_1 = i \sigma_3, & \sigma_2 \sigma_3 &= -\sigma_3 \sigma_2 = i \sigma_1, & \sigma_3 \sigma_1 &= -\sigma_1 \sigma_3 = i \sigma_2, \\ (\sigma_1)^2 &= (\sigma_2)^2 = (\sigma_3)^2 = I, \end{aligned}$$

where I is the 2×2 identity matrix. These nine equations are identical to identity (a) above.

$$(b) (\vec{\sigma} \cdot \vec{a})(\vec{\sigma} \cdot \vec{b}) = (\vec{a} \cdot \vec{b})I + i \vec{\sigma} \cdot (\vec{a} \times \vec{b}),$$

Multiply identity (a) above by $a_i b_j$ and sum over i and j , where each index can take on three values, 1, 2, and 3. Note the following results:

$$\sum_{i=1}^3 \sigma_i a_i = \vec{\sigma} \cdot \vec{a}, \quad \sum_{j=1}^3 \sigma_j b_j = \vec{\sigma} \cdot \vec{b}, \quad \sum_{i=1}^3 \sum_{j=1}^3 \delta_{ij} a_i b_j = \vec{a} \cdot \vec{b}.$$

Moreover, using

$$\sum_{i=1}^3 \sum_{j=1}^3 \epsilon_{ijk} a_i b_j = (\vec{a} \times \vec{b})_k,$$

it follows that:

$$\sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \epsilon_{ijk} a_i b_j \sigma_k = \vec{\sigma} \cdot (\vec{a} \times \vec{b}),$$

and we immediately obtain identity (b). That is, identity (b) is really identity (a) in disguise!

$$(c) \exp\left(-\frac{i}{2}\theta \hat{w} \cdot \vec{\sigma}\right) = I \cos(\theta/2) - i \hat{w} \cdot \vec{\sigma} \sin(\theta/2),$$

where I is the 2×2 identity matrix, \vec{a} and \vec{b} are ordinary vectors, and \hat{w} is a unit vector.

Using the series expansion for the matrix exponential,

$$\exp\left(-\frac{i}{2}\theta \hat{w} \cdot \vec{\sigma}\right) = \sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{-i\theta}{2}\right)^n (\hat{w} \cdot \vec{\sigma})^n. \quad (3)$$

Using identity (b) above, it follows that

$$(\hat{\mathbf{w}} \cdot \vec{\sigma})^2 = (\hat{\mathbf{w}} \cdot \vec{\sigma})(\hat{\mathbf{w}} \cdot \vec{\sigma}) = I,$$

where we have used the fact that $\hat{\mathbf{w}}$ is a unit vector to obtain $\hat{\mathbf{w}} \cdot \hat{\mathbf{w}} = 1$ (and of course, $\hat{\mathbf{w}} \times \hat{\mathbf{w}} = 0$). Hence, for any integer n ,

$$(\hat{\mathbf{w}} \cdot \vec{\sigma})^{2n} = I, \quad (\hat{\mathbf{w}} \cdot \vec{\sigma})^{2n+1} = \hat{\mathbf{w}} \cdot \vec{\sigma}.$$

Inserting these results back into the series [eq. (3)] we obtain:

$$\begin{aligned} \exp\left(-\frac{i}{2}\theta \hat{\mathbf{w}} \cdot \vec{\sigma}\right) &= I \sum_{n=0}^{\infty} \frac{1}{(2n)!} \left(\frac{-i\theta}{2}\right)^{2n} + \hat{\mathbf{w}} \cdot \vec{\sigma} \sum_{n=0}^{\infty} \frac{1}{(2n+1)!} \left(\frac{-i\theta}{2}\right)^{2n+1} \\ &= I \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n)!} \left(\frac{\theta}{2}\right)^{2n} - i\hat{\mathbf{w}} \cdot \vec{\sigma} \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n+1)!} \left(\frac{\theta}{2}\right)^{2n+1} \\ &= I \cos(\theta/2) - i\hat{\mathbf{w}} \cdot \vec{\sigma} \sin(\theta/2), \end{aligned}$$

after summing up the well known series for the sine and cosine, and noting that $(-i)^{2n} = (-1)^n$.

4. Consider the spinor $\alpha \equiv |\frac{1}{2}, \frac{1}{2}\rangle_{\hat{\mathbf{z}}}$ [cf. eq.(11.72) of Liboff]. I explicitly exhibit the subscript $\hat{\mathbf{z}}$ to emphasize that $|\frac{1}{2}, \frac{1}{2}\rangle_{\hat{\mathbf{z}}}$ is an eigenstate of S_z with eigenvalue $\frac{1}{2}\hbar$.

(a) Show (either geometrically or algebraically) that if the z -axis is rotated by an angle θ about a fixed axis $\hat{\mathbf{w}} = (-\sin \phi, \cos \phi, 0)$ [where the right-hand rule defines the direction of the unit vector $\hat{\mathbf{w}}$ perpendicular to the rotation plane], then the z -axis will end up pointing along the direction given by

$$\hat{\mathbf{n}} = (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta).$$

Consider the active rotation of a unit vector, $\hat{\mathbf{z}}$, that ends up pointing along the $\hat{\mathbf{n}}$ direction, where $\hat{\mathbf{n}}$ is a vector that points in a direction with polar angle θ (with respect to the z -axis) and azimuthal angle ϕ (defined in the usual way by projecting $\hat{\mathbf{n}}$ in the x - y plane and measuring the angle with respect to the x -axis). Note that in performing this rotation, we have rotated $\hat{\mathbf{z}}$ by an angle θ about a fixed axis, $\hat{\mathbf{w}}$, which lies in the x - y plane perpendicular to the plane containing $\hat{\mathbf{z}}$ and $\hat{\mathbf{n}}$. The direction of $\hat{\mathbf{w}}$ is determined by the right hand rule. I claim that:

$$\hat{\mathbf{w}} = \frac{\hat{\mathbf{z}} \times \hat{\mathbf{n}}}{|\hat{\mathbf{z}} \times \hat{\mathbf{n}}|},$$

where $|\hat{\mathbf{z}} \times \hat{\mathbf{n}}|$ is the length of the vector $\hat{\mathbf{z}} \times \hat{\mathbf{n}}$. This vector clearly satisfies the property that $\hat{\mathbf{z}} \times \hat{\mathbf{n}}$ is perpendicular to the plane containing $\hat{\mathbf{z}}$ and $\hat{\mathbf{n}}$ as required. Moreover, $\hat{\mathbf{z}} \times \hat{\mathbf{n}}$ points in a direction that is determined by the right-hand rule.

To complete the proof, simply compute $\hat{\mathbf{z}} \times \hat{\mathbf{n}}$.

$$\begin{aligned}\hat{\mathbf{z}} \times \hat{\mathbf{n}} &= \det \begin{pmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ 0 & 0 & 1 \\ \sin \theta \cos \phi & \sin \theta \sin \phi & \cos \theta \end{pmatrix} \\ &= -\hat{\mathbf{x}} \sin \theta \sin \phi + \hat{\mathbf{y}} \sin \theta \cos \phi.\end{aligned}$$

The length of the vector $\hat{\mathbf{z}} \times \hat{\mathbf{n}}$ is

$$|\hat{\mathbf{z}} \times \hat{\mathbf{n}}| = [\sin^2 \theta \sin^2 \phi + \sin^2 \theta \cos^2 \phi]^{1/2} = \sin \theta,$$

Hence, we conclude that

$$\hat{\mathbf{w}} = \frac{\hat{\mathbf{z}} \times \hat{\mathbf{n}}}{|\hat{\mathbf{z}} \times \hat{\mathbf{n}}|} = -\hat{\mathbf{x}} \sin \phi + \hat{\mathbf{y}} \cos \phi = (-\sin \phi, \cos \phi, 0).$$

(b) Define $|\frac{1}{2}, \frac{1}{2}\rangle_{\hat{\mathbf{n}}}$ to be an eigenstate of $\vec{\mathbf{S}} \cdot \hat{\mathbf{n}}$ with eigenvalue $\frac{1}{2}\hbar$. Express $|\frac{1}{2}, \frac{1}{2}\rangle_{\hat{\mathbf{n}}}$ with respect to the basis $\alpha = |\frac{1}{2}, \frac{1}{2}\rangle_{\hat{\mathbf{z}}} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $\beta = |\frac{1}{2}, -\frac{1}{2}\rangle_{\hat{\mathbf{z}}} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$.

Using $\vec{\mathbf{S}} = \frac{1}{2}\hbar\vec{\sigma}$, we can work out the dot product, $\vec{\mathbf{S}} \cdot \hat{\mathbf{n}}$:

$$\vec{\mathbf{S}} \cdot \hat{\mathbf{n}} = \frac{\hbar}{2} \begin{pmatrix} \cos \theta & \sin \theta e^{-i\phi} \\ \sin \theta e^{i\phi} & -\cos \theta \end{pmatrix}.$$

In class, we worked out the eigenvectors of $\vec{\mathbf{S}} \cdot \hat{\mathbf{n}}$. The eigenvector corresponding to eigenvalue $\frac{1}{2}\hbar$ is given by

$$|\frac{1}{2}, \frac{1}{2}\rangle_{\hat{\mathbf{n}}} = e^{i\delta} \begin{pmatrix} \cos(\theta/2)e^{-i\phi/2} \\ \sin(\theta/2)e^{i\phi/2} \end{pmatrix}, \quad (4)$$

where $e^{i\delta}$ is an arbitrary phase factor. This means that we can write:

$$|\frac{1}{2}, \frac{1}{2}\rangle_{\hat{\mathbf{n}}} = e^{i\delta} [\alpha \cos(\theta/2)e^{-i\phi/2} + \beta \sin(\theta/2)e^{i\phi/2}].$$

(c) Define $R_{\hat{\mathbf{w}}}(\theta)$ to be the rotation operator that corresponds to a rotation of state vectors by an angle θ about the $\hat{\mathbf{w}}$ axis [defined in part (a)]. For a spin- $\frac{1}{2}$ particle, I claim that

$$R_{\hat{\mathbf{w}}}(\theta) = \exp \left(-\frac{i}{2}\theta \hat{\mathbf{w}} \cdot \vec{\sigma} \right).$$

Let us put this operator to the test. Prove that

$$R_{\hat{\mathbf{w}}}(\theta) |\frac{1}{2}, \frac{1}{2}\rangle_{\hat{\mathbf{z}}} = |\frac{1}{2}, \frac{1}{2}\rangle_{\hat{\mathbf{n}}}.$$

First, note that since $\hat{\mathbf{w}} = (-\sin \phi, \cos \phi, 0)$, it follows that:

$$\hat{\mathbf{w}} \cdot \vec{\sigma} = \begin{pmatrix} 0 & -\sin \phi - i \cos \phi \\ -\sin \phi + i \cos \phi & 0 \end{pmatrix} = -i \begin{pmatrix} 0 & e^{-i\phi} \\ -e^{i\phi} & 0 \end{pmatrix}.$$

Using the result of problem 3(c),

$$\begin{aligned} R_{\hat{w}}(\theta) &= \exp\left(-\frac{i}{2}\theta\hat{w}\cdot\vec{\sigma}\right) = I \cos(\theta/2) - i\hat{w}\cdot\vec{\sigma} \sin(\theta/2) \\ &= \begin{pmatrix} \cos(\theta/2) & -e^{-i\phi} \sin(\theta/2) \\ e^{i\phi} \sin(\theta/2) & \cos(\theta/2) \end{pmatrix}. \end{aligned}$$

Using the fact that the state $|\frac{1}{2}, \frac{1}{2}\rangle_{\hat{z}}$ is represented by $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$, it follows that:

$$\begin{aligned} R_{\hat{w}}(\theta) |\frac{1}{2}, \frac{1}{2}\rangle_{\hat{z}} &= \begin{pmatrix} \cos(\theta/2) & -e^{-i\phi} \sin(\theta/2) \\ e^{i\phi} \sin(\theta/2) & \cos(\theta/2) \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} \cos(\theta/2) \\ e^{i\phi} \sin(\theta/2) \end{pmatrix} = e^{i\phi/2} \begin{pmatrix} \cos(\theta/2)e^{-i\phi/2} \\ \sin(\theta/2)e^{i\phi/2} \end{pmatrix}. \end{aligned}$$

Indeed, $R_{\hat{w}}(\theta) |\frac{1}{2}, \frac{1}{2}\rangle_{\hat{z}}$ is an eigenstate of $\vec{S} \cdot \hat{n}$ with eigenvalue $\frac{1}{2}\hbar$. Thus, choosing $\delta = \phi/2$ in eq. (4), we conclude that:

$$R_{\hat{w}}(\theta) |\frac{1}{2}, \frac{1}{2}\rangle_{\hat{z}} = |\frac{1}{2}, \frac{1}{2}\rangle_{\hat{n}}.$$

5. Consider a spin- $\frac{1}{2}$ particle of magnetic moment $\vec{\mu} = \gamma\vec{S}$, where $\gamma \equiv e/mc$. At time $t = 0$, the state of the system is given by $\alpha \equiv |\frac{1}{2}, \frac{1}{2}\rangle_{\hat{z}}$ (i.e., spin-up).

(a) If the observable S_x is measured at time $t = 0$, what results can be found and with what probabilities?

To see what the possible results of a measurement of S_x , consider the initial state, $|\frac{1}{2}, \frac{1}{2}\rangle_{\hat{z}}$. Expand this state in terms of the two possible states, $|\frac{1}{2}, \frac{1}{2}\rangle_{\hat{x}}$ and $|\frac{1}{2}, -\frac{1}{2}\rangle_{\hat{x}}$ that can result from a measurement of S_x . These two states are the normalized eigenstates of $S_x = \frac{1}{2}\hbar\sigma_x$, namely,

$$|\frac{1}{2}, \frac{1}{2}\rangle_{\hat{x}} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad |\frac{1}{2}, -\frac{1}{2}\rangle_{\hat{x}} = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}. \quad (5)$$

Using the above results, it is easy to determine that:

$$|\frac{1}{2}, \frac{1}{2}\rangle_{\hat{z}} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{2}} |\frac{1}{2}, \frac{1}{2}\rangle_{\hat{x}} - \frac{1}{\sqrt{2}} |\frac{1}{2}, -\frac{1}{2}\rangle_{\hat{x}}.$$

The possible measurements of S_x yield either $\frac{1}{2}\hbar$ or $-\frac{1}{2}\hbar$, with equal probabilities of $\frac{1}{2}$ in the two cases (corresponding to the absolute square of the coefficients of $|\frac{1}{2}, \pm\frac{1}{2}\rangle_{\hat{x}}$ above).

(b) Instead of performing the measurement specified in part (a), we let the system evolve under the influence of a uniform magnetic field B parallel to the

y -axis (i.e., $\vec{B} = B\hat{y}$ with $B > 0$). Calculate the state of the system at time t with respect to the $\{\alpha, \beta\}$ basis.

The Hamiltonian of the system is

$$H = -\gamma \vec{S} \cdot \vec{B} = -\gamma B S_y = -\frac{1}{2}\hbar\gamma B\sigma_y.$$

Thus, $|\psi(t)\rangle = U(t)|\psi(0)\rangle$, where

$$U(t) = e^{-iHt/\hbar} = \exp\left(\frac{1}{2}i\gamma B\sigma_y t\right).$$

Let us define $\omega_0 \equiv -\gamma B$. Then,

$$\begin{aligned} U(t) &= \exp\left(-\frac{1}{2}i\omega_0 t\sigma_y\right) = I \cos(\omega_0 t/2) - i\sigma_y \sin(\omega_0 t/2) \\ &= \begin{pmatrix} \cos(\omega_0 t/2) & -\sin(\omega_0 t/2) \\ \sin(\omega_0 t/2) & \cos(\omega_0 t/2) \end{pmatrix}. \end{aligned}$$

Here we have used the results of problem 3(c), and have identified $\hat{w} = (0, 1, 0)$. Note that it is critical that \hat{w} is a *unit* vector. This requirement allows us to unambiguously identify $\theta \equiv \omega_0 t$.

Hence, the state of the system at time t is:

$$|\psi(t)\rangle = U(t) \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \cos(\omega_0 t/2) \\ \sin(\omega_0 t/2) \end{pmatrix} = \alpha \cos(\omega_0 t/2) + \beta \sin(\omega_0 t/2). \quad (6)$$

(c) At a fixed time $t = T > 0$, we measure one of the observables S_x , S_y and S_z . For each case, what values can be found and with what probabilities? Is there any value of B (which may depend on T) such that one of the above measurements yields a unique result?

We now measure either S_x , S_y or S_z . To address each case separately, we should expand the spinor obtained in part (b) in terms of a new basis consisting of the eigenstates of S_x , S_y or S_z , respectively.

First, we expand in terms of eigenstates of S_z . But, this has already been done in part (b):

$$|\psi(t)\rangle = \cos(\omega_0 t/2) \left| \frac{1}{2}, \frac{1}{2} \right\rangle_{\hat{z}} + \sin(\omega_0 t/2) \left| \frac{1}{2}, -\frac{1}{2} \right\rangle_{\hat{z}}.$$

Thus the possible results obtained by measuring S_z are:

$$\begin{aligned} +\frac{1}{2}\hbar, & \quad \text{with probability} \quad \cos^2(\omega_0 t/2) = \frac{1}{2}(1 + \cos \omega_0 t), \\ -\frac{1}{2}\hbar, & \quad \text{with probability} \quad \sin^2(\omega_0 t/2) = \frac{1}{2}(1 - \cos \omega_0 t), \end{aligned}$$

where the probabilities are identified as the absolute squares of the coefficients of $\left| \frac{1}{2}, \pm \frac{1}{2} \right\rangle_{\hat{z}}$, respectively.

Second, we expand $|\psi(t)\rangle$ in terms of eigenstates of S_x :

$$|\psi(t)\rangle = c_+ \left| \frac{1}{2}, \frac{1}{2} \right\rangle_{\hat{x}} + c_- \left| \frac{1}{2}, -\frac{1}{2} \right\rangle_{\hat{x}},$$

where²

$$c_{\pm} = \hat{x} \langle \frac{1}{2}, \pm \frac{1}{2} | \psi(t) \rangle.$$

Using eqs. (5) and (6), one can easily evaluate c_{\pm} ,

$$c_+ = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \cos(\omega_0 t/2) \\ \sin(\omega_0 t/2) \end{pmatrix} = \frac{1}{\sqrt{2}} [\cos(\omega_0 t/2) + \sin(\omega_0 t/2)],$$

$$c_- = \begin{pmatrix} -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \cos(\omega_0 t/2) \\ \sin(\omega_0 t/2) \end{pmatrix} = \frac{1}{\sqrt{2}} [-\cos(\omega_0 t/2) + \sin(\omega_0 t/2)].$$

To get the relevant probabilities, we need to square these results:

$$|c_+|^2 = \frac{1}{2} [\sin^2(\omega_0 t/2) + \cos^2(\omega_0 t/2) + 2 \sin(\omega_0 t/2) \cos(\omega_0 t/2)] = \frac{1}{2} [1 + \sin(\omega_0 t)],$$

$$|c_-|^2 = \frac{1}{2} [\sin^2(\omega_0 t/2) + \cos^2(\omega_0 t/2) - 2 \sin(\omega_0 t/2) \cos(\omega_0 t/2)] = \frac{1}{2} [1 - \sin(\omega_0 t)].$$

Hence, the possible results obtained by measuring S_x are:

$$+\frac{1}{2}\hbar, \quad \text{with probability } \frac{1}{2}(1 + \sin \omega_0 t),$$

$$-\frac{1}{2}\hbar, \quad \text{with probability } \frac{1}{2}(1 - \sin \omega_0 t).$$

Finally, we expand $|\psi(t)\rangle$ in terms of eigenstates of S_y . Here, we note that the normalized eigenstates of $S_y = \frac{1}{2}\hbar\sigma_y$ are:

$$\left| \frac{1}{2}, \frac{1}{2} \right\rangle_{\hat{y}} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}, \quad \left| \frac{1}{2}, -\frac{1}{2} \right\rangle_{\hat{y}} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -i \end{pmatrix}. \quad (7)$$

Following the previous computation, we write:

$$|\psi(t)\rangle = c_+ \left| \frac{1}{2}, \frac{1}{2} \right\rangle_{\hat{y}} + c_- \left| \frac{1}{2}, -\frac{1}{2} \right\rangle_{\hat{y}},$$

where

$$c_{\pm} = \hat{y} \langle \frac{1}{2}, \pm \frac{1}{2} | \psi(t) \rangle.$$

Using eqs. (6) and (7), one can easily evaluate c_{\pm} . Keep in mind that in this computation, the adjoint spinor $\hat{y} \langle \frac{1}{2}, \pm \frac{1}{2} |$ appears, so we have to complex conjugate the results of eq. (7), which changes the sign of i . Hence,

$$c_+ = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{-i}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \cos(\omega_0 t/2) \\ \sin(\omega_0 t/2) \end{pmatrix} = \frac{1}{\sqrt{2}} e^{-i\omega_0 t/2},$$

$$c_- = \begin{pmatrix} -\frac{1}{\sqrt{2}} & \frac{i}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \cos(\omega_0 t/2) \\ \sin(\omega_0 t/2) \end{pmatrix} = \frac{1}{\sqrt{2}} e^{i\omega_0 t/2}.$$

²Here, we are using the fact that we can expand any state $|\psi\rangle$ in terms of a complete basis $\{e_1, e_2\}$ as follows: $|\psi\rangle = \sum_{i=1}^2 |e_i\rangle \langle e_i| \psi\rangle$. In this case, the complete basis is made up of $\left| \frac{1}{2}, \pm \frac{1}{2} \right\rangle_{\hat{x}}$.

To get the relevant probabilities, we need to square these results, which yields $|c_{\pm}|^2 = \frac{1}{2}$. Hence, the possible results obtained by measuring S_y are:

$$\begin{aligned} +\frac{1}{2}\hbar, & \text{ with probability } \frac{1}{2}, \\ -\frac{1}{2}\hbar, & \text{ with probability } \frac{1}{2}. \end{aligned}$$

Thus, the measurement of S_y *never* gives a unique result. This could have been anticipated, since at $t = 0$, the initial state $|\frac{1}{2}, \frac{1}{2}\rangle_z$ is equally likely to be either spin-up or spin-down with respect to the y -axis. But, a B field applied in the $\hat{\mathbf{y}}$ direction does not modify the y -component of the spin.

However, the measurement of S_x and S_z can give unique results at some fixed time $t = T \geq 0$, if B (or equivalently, $\omega_0 \equiv -\gamma B$) takes on particular values. Noting that for any integer n ,

$$\cos(n\pi) = (-1)^n, \quad \sin[(n + \frac{1}{2})\pi] = (-1)^n,$$

we see that:

- If $\omega_0 T = n\pi$, then the measurement of S_z yields:
 1. pure spin up, if n is even,
 2. pure spin down, if n is odd.
- If $\omega_0 T = (n + \frac{1}{2})\pi$, then the measurement of S_x yields:
 1. pure spin up, if n is even,
 2. pure spin down, if n is odd.

Using $\omega_0 \equiv -\gamma B$, it follows that the measurement of S_x is unique if

$$B = \frac{n + \frac{1}{2}}{|\gamma|T}, \quad \text{for } n = 0, 1, 2, \dots,$$

and the measurement of S_z is unique if

$$B = \frac{n\pi}{|\gamma|T}, \quad \text{for } n = 1, 2, 3, \dots.$$

Note that the integer n is restricted to non-negative values in the first case and positive values in the second case, since by assumption $T \geq 0$ (and $B > 0$). Finally, as previously noted, the measurement of S_y is never unique.